

The Unreasonable Effectiveness of Logic

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Is computing a deep subject?

POWER SHOVEL

Small shovel

This power shovel is a small one. It is only 11 metres (36 feet) long and weighs a mere 6 tonnes (just under 6 tons).

Open and shut

This ram uses oil pressure to transmit the force of a piston to the bucket bottom. This system, called a hydraulic ram, opens and closes the bucket.

Up and down

This hydraulic ram raises and lowers the boom.

Bucket

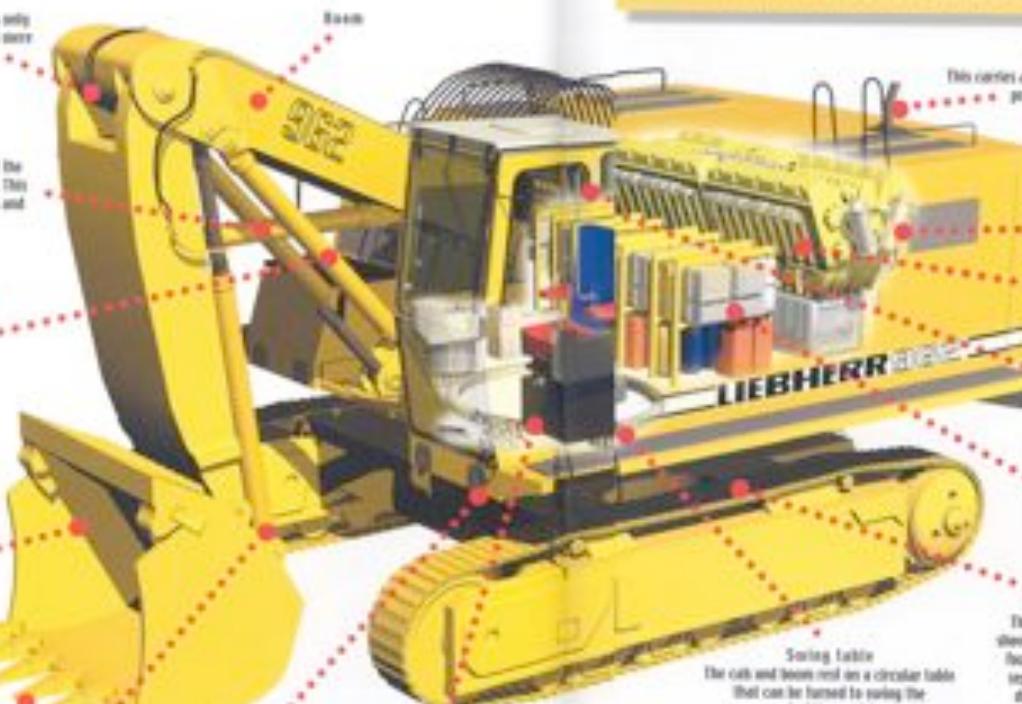
The bucket is hinged in the middle so it can open to drop a load. Some very big mining shovels have eight buckets fitted to a large wheel that revolves as the machine cuts into the coal-face.

Replaceable teeth

The teeth on the bucket are designed to sharpen themselves as they cut into the coal-face. They can be replaced when they eventually wear out.

Bucket hinge

The bucket opens and shuts here.



COMPUTER CONTROLS

Moving machines such as the power shovel need to be carefully controlled, or they could do a lot of damage. If they are overloaded or break down they are extremely expensive to repair. So the power shovel has built-in computer systems that automatically shut down the engine if there is a danger of overload. Sensors fitted around the shovel monitor engine performance, temperature and oil pressure. The computer gives a warning if the engine is not operating properly.

Air filter

This filters (or separates) out the dust in the air, ensuring that only clean air goes to the engine.

Engines

The shovel has two powerful diesel engines. If one engine breaks down, the other takes over.

Liebherr's cab

The cab is 4 metres (13 feet) from the ground. It is sound- and vibration-proof. The operator pulls levers to move the boom, and to open and close the bucket.

Oil tank

This holds the oil used in the hydraulic systems.

Crawler tracks

These are driven by the diesel engine. The shovel can move around safely on the soft soil found in open-cast mines. The tracks work separately. To turn the shovel, one track is driven forward while the other is driven backwards or kept still.

BIG DIGGER

A power shovel digs coal out of the walls of an open-cast coal mine. This massive machine has a huge bucket at the end of a long arm or boom – it carries up to 140 cubic metres (1,907 cubic feet) of coal. The boom stretches up the coal face to scrape out coal with the bucket. When the bucket is full, the driver swings the arm round and drops the coal on to a waiting lorry. A power shovel works fast – it can fill a large lorry with 120 tonnes (138 tons) of coal in just two minutes. Power shovels are driven by petrol or diesel engines, or by electric motors.

The Marion 6340 power shovel has a boom length of 67 metres (220 feet) and a reach of 72 metres (236 feet). It weighs 1,100 tonnes (1,082 tons) and uses 20 electric motors to power the boom and bucket. It works in an open-cast coal mine near Poccy in Illinois, USA.

Theoretical computer science is unnatural ...

... but is it unnatural like Ikebana?



... or is it unnatural like Judo?





More than a coincidence?

second-order logic

polymorphism

Java

modal logic

monads

XML

classical logic

continuations

Links

Part I

A remarkable coincidence

Gerhard Gentzen (1909–1945)



Gerhard Gentzen (1935) – Natural Deduction

$\&-I$

$$\frac{\mathfrak{A} \quad \mathfrak{B}}{\mathfrak{A} \& \mathfrak{B}}$$

$\&-E$

$$\frac{\mathfrak{A} \& \mathfrak{B}}{\mathfrak{A}} \quad \frac{\mathfrak{A} \& \mathfrak{B}}{\mathfrak{B}}$$

$\vee-I$

$$\frac{\mathfrak{A}}{\mathfrak{A} \vee \mathfrak{B}} \quad \frac{\mathfrak{B}}{\mathfrak{A} \vee \mathfrak{B}}$$

$\vee-E$

$$\frac{\begin{array}{c} [\mathfrak{A}] \\ \mathfrak{A} \vee \mathfrak{B} \end{array} \quad \begin{array}{c} [\mathfrak{B}] \\ \mathfrak{C} \end{array}}{\mathfrak{C}}$$

$\forall-I$

$$\frac{\tilde{\mathfrak{F}}\mathfrak{a}}{\forall x \tilde{\mathfrak{F}}x}$$

$\forall-E$

$$\frac{\forall x \tilde{\mathfrak{F}}x}{\tilde{\mathfrak{F}}\mathfrak{a}}$$

$\exists-I$

$$\frac{\tilde{\mathfrak{F}}\mathfrak{a}}{\exists x \tilde{\mathfrak{F}}x}$$

$\exists-E$

$$\frac{\begin{array}{c} [\tilde{\mathfrak{F}}\mathfrak{a}] \\ \exists x \tilde{\mathfrak{F}}x \end{array} \quad \mathfrak{C}}{\mathfrak{C}}$$

$\supset-I$

$$\frac{\begin{array}{c} [\mathfrak{A}] \\ \mathfrak{B} \end{array}}{\mathfrak{A} \supset \mathfrak{B}}$$

$\supset-E$

$$\frac{\mathfrak{A} \quad \mathfrak{A} \supset \mathfrak{B}}{\mathfrak{B}}$$

$\neg\neg-I$

$$\frac{[\mathfrak{A}]}{\neg \mathfrak{A}}$$

$\neg\neg-E$

$$\frac{\begin{array}{c} \mathfrak{A} \neg \mathfrak{A} \\ \neg \mathfrak{A} \end{array} \quad \begin{array}{c} \mathfrak{A} \\ \mathfrak{D} \end{array}}{\mathfrak{D}}$$

Gerhard Gentzen (1935) – Natural Deduction

$$\frac{\begin{array}{c} [A]^x \\ \vdots \\ B \end{array}}{A \supset B} \supset\text{-I}^x \qquad \frac{A \supset B \quad A}{B} \supset\text{-E}$$

$$\frac{A \quad B}{A \& B} \&\text{-I} \qquad \frac{A \& B}{A} \&\text{-E}_0 \qquad \frac{A \& B}{B} \&\text{-E}_1$$

Simplifying a proof

$$\frac{\frac{\frac{[B \& A]^z}{A} \&\text{-E}_1 \quad \frac{[B \& A]^z}{B} \&\text{-E}_0}{A \& B} \&\text{-I}}{(B \& A) \supset (A \& B)} \supset\text{-I}^z \quad \frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I}}{A \& B} \supset\text{-E}$$

Simplifying a proof

$$\frac{\frac{\frac{[B \& A]^z}{A} \&\text{-E}_1 \quad \frac{[B \& A]^z}{B} \&\text{-E}_0}{A \& B} \&\text{-I}}{(B \& A) \supset (A \& B)} \supset\text{-I}^z \quad \frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I}}{A \& B} \supset\text{-E}$$

\Downarrow

$$\frac{\frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I} \quad \frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I}}{A \& B} \&\text{-I}$$

Simplifying a proof

$$\frac{\frac{\frac{[B \& A]^z}{A} \&\text{-E}_1 \quad \frac{[B \& A]^z}{B} \&\text{-E}_0}{A \& B} \&\text{-I}}{(B \& A) \supset (A \& B)} \supset\text{-I}^z \quad \frac{\frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I}}{A \& B} \supset\text{-E}}$$
$$\Downarrow$$
$$\frac{\frac{\frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I} \quad \frac{[B]^y \quad [A]^x}{B \& A} \&\text{-I}}{A \& \text{-E}_1 \quad B \& \text{-E}_0}{\&\text{-I}}}{A \& B}$$
$$\Downarrow$$
$$\frac{[A]^x \quad [B]^y}{A \& B} \&\text{-I}$$

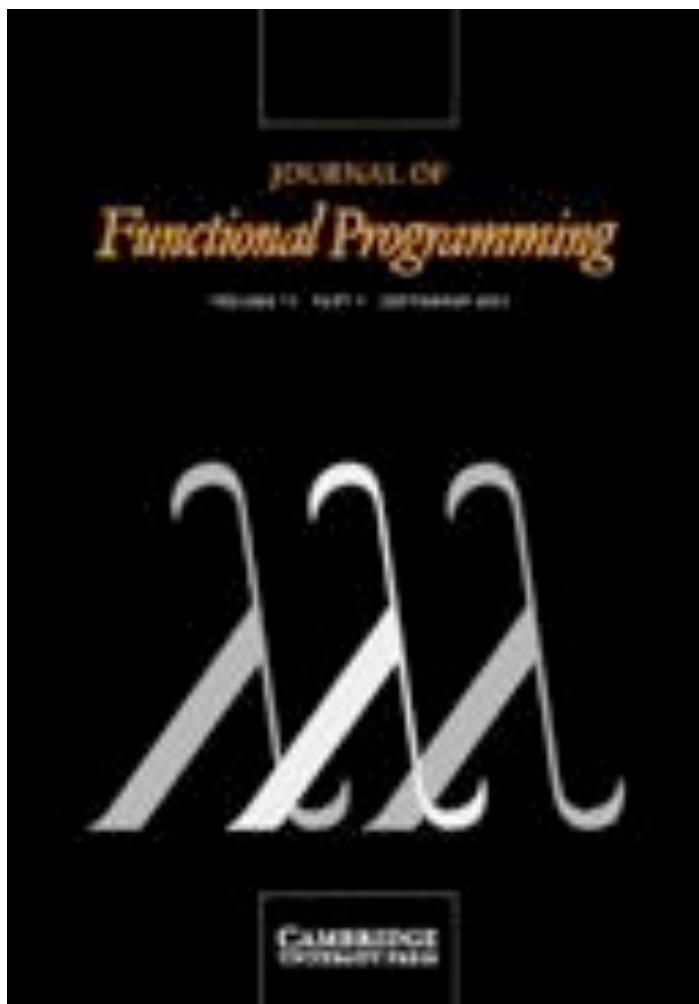
Alonzo Church (1903–1995)



Alonzo Church (1932) — Lambda calculus

An occurrence of a variable x in a given formula is called an occurrence of x as a *bound variable* in the given formula if it is an occurrence of x in a part of the formula of the form $\lambda x[M]$; that is, if there is a formula M such that $\lambda x[M]$ occurs in the given formula and the occurrence of x in question is an occurrence in $\lambda x[M]$. All other occurrences of a variable in a formula are called occurrences as a *free variable*.

A formula is said to be *well-formed* if it is a variable, or if it is one





Alonzo Church (1940) – Typed λ -calculus

$$\frac{\begin{array}{c} [x : A]^x \\ \vdots \\ u : B \end{array}}{\lambda x. u : A \supset B} \supset\text{-I}^x \quad \frac{s : A \supset B \quad t : A}{s t : B} \supset\text{-E}$$

$$\frac{t : A \quad u : B}{\langle t, u \rangle : A \& B} \&\text{-I} \quad \frac{s : A \& B}{s_0 : A} \&\text{-E}_0 \quad \frac{s : A \& B}{s_1 : B} \&\text{-E}_1$$

Simplifying a program

$$\frac{\frac{[z : B \& A]^z}{z_1 : A} \&\text{-E}_1 \quad \frac{[z : B \& A]^z}{z_0 : B} \&\text{-E}_0}{\frac{\langle z_1, z_0 \rangle : A \& B}{\lambda z. \langle z_1, z_0 \rangle : (B \& A) \supset (A \& B)}} \supset\text{-I}^z \quad \frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\supset\text{-E}} \quad (\lambda z. \langle z_1, z_0 \rangle) \langle y, x \rangle : A \& B$$

Simplifying a program

$$\frac{\frac{\frac{[z : B \& A]^z}{z_1 : A} \&\text{-E}_1 \quad \frac{[z : B \& A]^z}{z_0 : B} \&\text{-E}_0}{\langle z_1, z_0 \rangle : A \& B} \&\text{-I}}{\lambda z. \langle z_1, z_0 \rangle : (B \& A) \supset (A \& B)} \supset\text{-I}^z \quad \frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\langle \lambda z. \langle z_1, z_0 \rangle \rangle \langle y, x \rangle : A \& B} \supset\text{-E}$$

\Downarrow

$$\frac{\frac{\frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\langle y, x \rangle_1 : A} \&\text{-E}_1 \quad \frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\frac{\langle y, x \rangle_0 : B}{\langle \langle y, x \rangle_1, \langle y, x \rangle_0 \rangle : A \& B}} \&\text{-E}_0 \quad \&\text{-I}$$

Simplifying a program

$$\frac{\frac{\frac{[z : B \& A]^z}{z_1 : A} \&\text{-E}_1 \quad \frac{[z : B \& A]^z}{z_0 : B} \&\text{-E}_0}{\langle z_1, z_0 \rangle : A \& B} \&\text{-I}}{\lambda z. \langle z_1, z_0 \rangle : (B \& A) \supset (A \& B)} \supset\text{-I}^z \quad \frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\langle \lambda z. \langle z_1, z_0 \rangle \rangle \langle y, x \rangle : A \& B} \supset\text{-E}$$

↓

$$\frac{\frac{\frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\langle y, x \rangle_1 : A} \&\text{-E}_1 \quad \frac{[y : B]^y \quad [x : A]^x}{\langle y, x \rangle : B \& A} \&\text{-I}}{\frac{\langle y, x \rangle_0 : B}{\langle \langle y, x \rangle_1, \langle y, x \rangle_0 \rangle : A \& B}} \&\text{-E}_0 \&\text{-I}}$$

↓

$$\frac{[x : A]^x \quad [y : B]^y}{\langle x, y \rangle : A \& B} \&\text{-I}$$

William Howard (1980) — Curry-Howard Isomorphism

THE FORMULAE-AS-TYPES NOTION OF CONSTRUCTION

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Dedicated to H. B. Curry on the occasion of his 80th birthday.

The following consists of notes which were privately circulated in 1969. Since they have been referred to a few times in the literature, it seems worth while to publish them. They have been rearranged for easier reading, and some inessential corrections have been made.

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Part II

Second-order logic,
Polymorphism,
and Java

Gottlob Frege (1879) – Quantifiers (\forall)

It is clear also that from

$$\vdash \Phi(a) \\ \hline A$$

we can derive

$$\vdash \overset{a}{\sim} \Phi(a) \\ \hline A$$

if A is an expression in which a does not occur and if a stands only in the argument places of $\Phi(a)$.¹⁴ If $\overset{a}{\sim} \Phi(a)$ is denied, we must be able to specify a meaning for a such that $\Phi(a)$ will be denied. If, therefore, $\overset{a}{\sim} \Phi(a)$ were to be denied and

Gottlob Frege (1879) – Quantifiers (\forall)

If from the proposition that d has property F , whatever d may be, it can be inferred that every result of an application of the procedure f to d has property F , then property F is hereditary in the f -sequence.

§ 26.

$$\vdash \left[\begin{array}{c} \tilde{\gamma} \\ \text{---} \\ \tilde{\gamma}(y) \\ \text{---} \\ a \\ \text{---} \\ \tilde{\gamma}(a) \\ \text{---} \\ f(x, a) \\ \text{---} \\ \delta \\ \text{---} \\ \tilde{\gamma}(\alpha) \\ \text{---} \\ \alpha \\ \text{---} \\ f(\delta, \alpha) \end{array} \right] \equiv \frac{\gamma}{\beta} f(x_\gamma, y_\beta) \quad (76).$$

John Reynolds (1974) — Polymorphism

TOWARDS A THEORY OF TYPE STRUCTURE [†]

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Introduction

The type structure of programming languages has been the subject of an active development characterized by continued controversy over basic principles.⁽¹⁻⁷⁾ In this paper, we formalize a view of these principles somewhat similar to that of J. H. Morris.⁽⁵⁾ We introduce an extension of the typed lambda calculus which permits user-defined types and polymorphic functions, and show that the semantics of this language satisfies a representation theorem which embodies our notion of a "correct" type structure.

Syntax

To formalize the syntax of our language, we begin with two disjoint, countably infinite sets: the set T of type variables and the set V of normal variables. Then W , the set of type expressions, is the minimal set satisfying:

- (1a) If $t \in T$ then:
 $t \in W.$
- (1b) If $w_1, w_2 \in W$ then:
 $(w_1 + w_2) \in W.$
- (1c) If $t \in T$ and $w \in W$ then:
 $(\Delta t, w) \in W.$

Jean-Yves Girard (1972) – Polymorphism

UNE EXTENSION DE L'INTERPRETATION DE GÖDEL A L'ANALYSE, ET SON APPLICATION A L'ELIMINATION DES COUPURES DANS L'ANALYSE ET LA THEORIE DES TYPES

Jean-Yves GIRARD

(8, Rue du Moulin d'Amboise, 94-Sucy en Brie, France)

Ce travail comprend (Ch. 1–5) une interprétation de l'Analyse, exprimée dans la logique intuitionniste, dans un système de fonctionnelles Y , décrit Ch. 1, et qui est une extension du système connu de Gödel [Gd]. En gros, le système est obtenu par l'adjonction de deux sortes de types (respectivement existentiels et universels, si les types construits avec \rightarrow sont considérés comme implicationnels) et de quatre schémas de construction de fonctionnelles correspondant à l'introduction et à l'élimination de chacun de ces types, ainsi que par la donnée des règles de calcul (réductions) correspondantes.

Robin Milner (1975) — Polymorphism

A Theory of Type Polymorphism in Programming

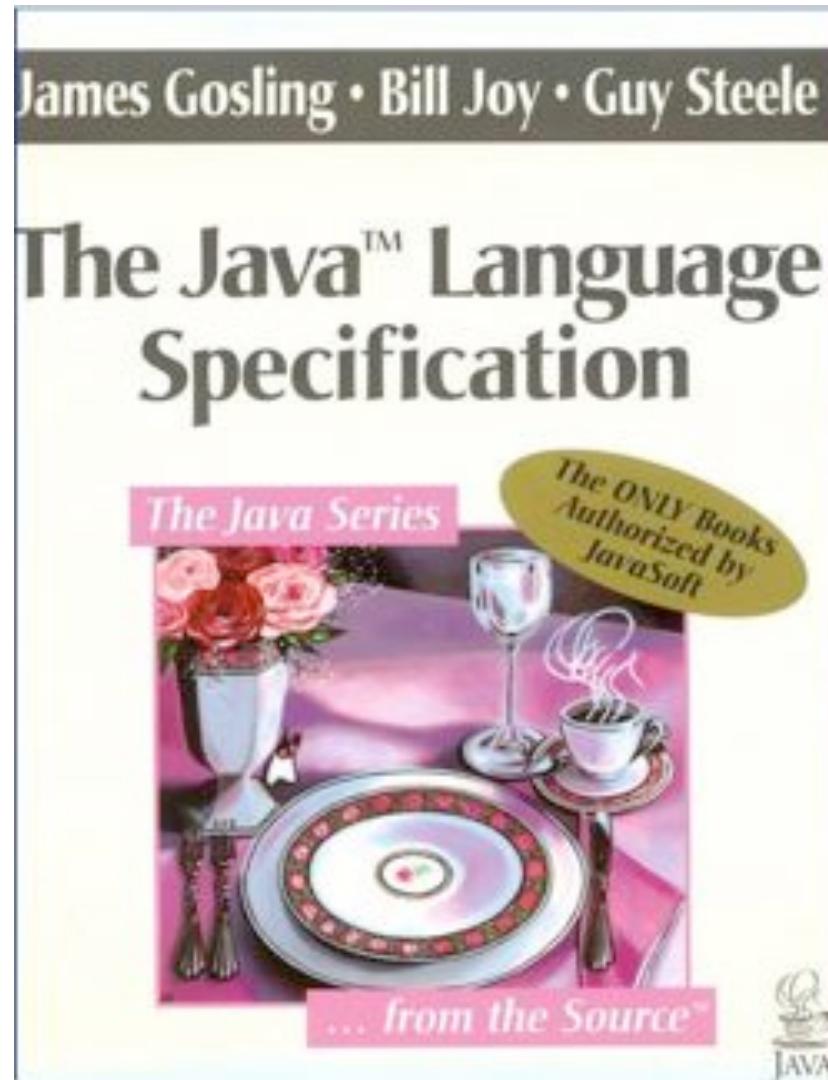
ROBIN MILNER

Computer Science Department, University of Edinburgh, Edinburgh, Scotland

Received October 10, 1977; revised April 19, 1978

The aim of this work is largely a practical one. A widely employed style of programming, particularly in structure-processing languages which impose no discipline of types, entails defining procedures which work well on objects of a wide variety. We present a formal type discipline for such polymorphic procedures in the context of a simple programming language, and a compile time type-checking algorithm \mathcal{W} which enforces the discipline. A Semantic Soundness Theorem (based on a formal semantics for the language) states that well-type programs cannot "go wrong" and a Syntactic Soundness Theorem states that if \mathcal{W} accepts a program then it is well typed. We also discuss extending these results to richer languages; a type-checking algorithm based on \mathcal{W} is in fact already implemented and working, for the metalanguage MI, in the Edinburgh LCF system.

Gosling, Joy, Steele (1996) — Java



Odersky and Wadler (1997) – Pizza

Example 2.1 Polymorphism in Pizza

```
class Pair<elem> {
    elem x; elem y;
    Pair (elem x, elem y) {this.x = x; this.y = y;}
    void swap () {elem t = x; x = y; y = t;}
}

Pair<String> p = new Pair("world!", "Hello.");
p.swap();
System.out.println(p.x + p.y);

Pair<int> q = new Pair(22, 64);
q.swap();
System.out.println(q.x - q.y);
```

Igarashi, Pierce, and Wadler (1999) — Featherweight Java

$$\Gamma \vdash x : \Gamma(x)$$

$$\frac{\Gamma \vdash e_0 : C_0 \quad \text{fields}(C_0) = \bar{C} \setminus \bar{E}}{\Gamma \vdash e_0.f_i : C_i}$$

$$\frac{\Gamma \vdash e_0 : C_0 \quad \text{mstype}(m, C_0) = \bar{D} \rightarrow \bar{C} \quad \Gamma \vdash \bar{e} : \bar{C} \quad \bar{C} \subset \bar{D}}{\Gamma \vdash e_0.m(\bar{e}) : C}$$

$$\frac{\text{fields}(C) = \bar{D} \setminus \bar{E} \quad \Gamma \vdash \bar{e} : \bar{C} \quad \bar{C} \subset \bar{D}}{\Gamma \vdash \text{new } C(\bar{e}) : C}$$

$$\frac{\Gamma \vdash e_0 : D \quad D \subset C}{\Gamma \vdash (C)e_0 : C}$$

$$\frac{\Gamma \vdash e_0 : D \quad C \subset D \quad C \neq D}{\Gamma \vdash (C)e_0 : C}$$

$$\frac{\Gamma \vdash e_0 : D \quad C \not\subset D \quad D \not\subset C \quad \text{stupid warning}}{\Gamma \vdash (C)e_0 : C}$$

Igarashi, Pierce, and Wadler (1999)

— Featherweight Generic Java

$$\Delta; \Gamma \vdash x : \Gamma(x)$$

$$\frac{\Delta; \Gamma \vdash e_0 : T_0 \quad \text{fields}(\text{bound}_{\Delta}(T_0)) = \bar{T} \bar{F}}{\Delta; \Gamma \vdash e_0.f_i : T_i}$$

$$\frac{\Delta; \Gamma \vdash e_0 : T_0 \quad \text{mtype}(n, \text{bound}_{\Delta}(T_0)) = \langle \bar{Y} \triangleleft \bar{P} \triangleright \bar{U} \rightarrow \bar{U} \quad \Delta \vdash \bar{V} \text{ ok} \quad \Delta \vdash \bar{V} \in [\bar{V}/\bar{Y}]\bar{P} \quad \Delta; \Gamma \vdash \bar{e} : \bar{S} \quad \Delta \vdash \bar{S} \in [\bar{V}/\bar{Y}]\bar{U}}{\Delta; \Gamma \vdash e_0.n<\bar{V}>(\bar{e}) : [\bar{V}/\bar{Y}]\bar{U}}$$

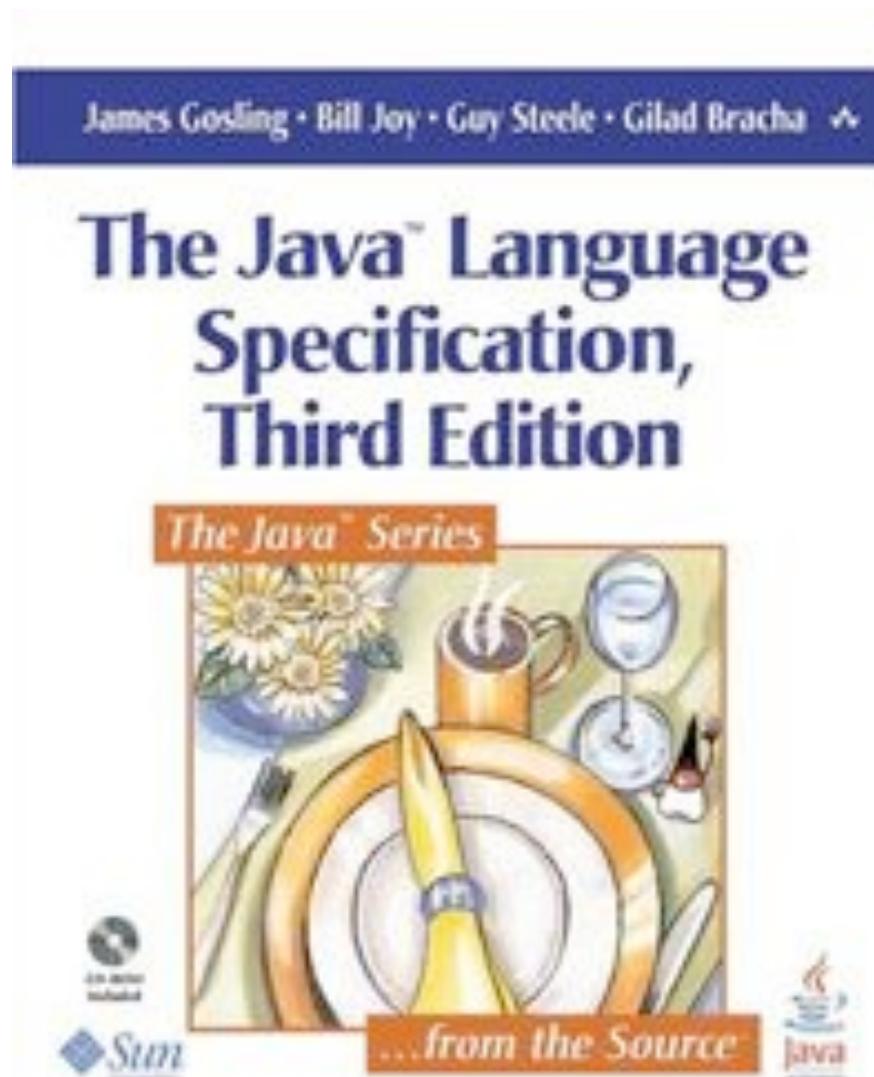
$$\frac{\Delta \vdash N \text{ ok} \quad \text{fields}(N) = \bar{T} \bar{F} \quad \Delta; \Gamma \vdash \bar{e} : \bar{S} \quad \Delta \vdash \bar{S} \in \bar{T}}{\Delta; \Gamma \vdash \text{new } N(\bar{e}) : N}$$

$$\frac{\Delta; \Gamma \vdash e_0 : T_0 \quad \Delta \vdash \text{bound}_{\Delta}(T_0) \in N}{\Delta; \Gamma \vdash (N)e_0 : N}$$

$$\frac{\Delta; \Gamma \vdash e_0 : T_0 \quad \Delta \vdash N \text{ ok} \quad \Delta \vdash N \in \text{bound}_{\Delta}(T_0) \quad N = C<\bar{T}> \quad \text{bound}_{\Delta}(T_0) = D<\bar{U}> \quad \text{doast}(C, D)}{\Delta; \Gamma \vdash (N)e_0 : N}$$

$$\frac{\Delta; \Gamma \vdash e_0 : T_0 \quad \Delta \vdash N \text{ ok} \quad N = C<\bar{T}> \quad \text{bound}_{\Delta}(T_0) = D<\bar{U}> \quad C \not\sqsubseteq D \quad D \not\sqsubseteq C \quad \text{stupid warning}}{\Delta; \Gamma \vdash (N)e_0 : N}$$

Gosling, Joy, Steele, Bracha (2004) — Java 5



Part III

Modality,
monads,
and XML

Clarence Lewis (1918) — Modal Logic

Systems previously developed, except MacColl's, have only two truth-values, "true" and "false". The addition of the idea of impossibility gives us five truth-values, all of which are familiar logical ideas:

- (1) p , " p is true".
- (2) $\neg p$, " p is false".
- (3) $\sim p$, " p is impossible".
- (4) $\sim\sim p$, "It is false that p is impossible"—i. e., " p is possible".
- (5) $\sim\sim p$, "It is impossible that p be false"—i. e., " p is necessarily true".

Strictly, the last two should be written $\neg(\sim p)$ and $\sim(\neg p)$: the parentheses are regularly omitted for typographical reasons.

Eugenio Moggi (1988) — Monads

Definition 2.1

A computational model is a monad (T, η, μ) over a category \mathcal{C} , i.e. a functor $T: \mathcal{C} \rightarrow \mathcal{C}$ and two natural transformations $\eta: \text{Id}_{\mathcal{C}} \rightarrow T$ and $\mu: T^2 \rightarrow T$ s.t.

$$\begin{array}{ccc} T^3 A & \xrightarrow{\mu_{TA}} & T^2 A \\ T\mu_A \downarrow & & \downarrow \mu_A \\ T^2 A & \xrightarrow{\mu_A} & TA \end{array} \quad \begin{array}{ccccc} TA & \xrightarrow{\eta_{TA}} & T^2 A & \xleftarrow{T\eta_A} & TA \\ \searrow \text{id}_{TA} & & \downarrow \mu_A & & \swarrow \text{id}_{TA} \\ & TA & & & \end{array}$$

which satisfies also an extra equalizing requirement: $\eta_A: A \rightarrow TA$ is an equalizer of η_{TA} and $T(\eta_A)$, i.e. for any $f: B \rightarrow TA$ s.t. $f; \eta_{TA} = f; T(\eta_A)$ there exists a unique $m: B \rightarrow A$ s.t. $f = m; \eta_A$ ³.

Philip Wadler (1990) – Comprehensions

2.2 Comprehensions

Many functional languages provide a form of *list comprehension* analogous to set comprehension. For example,

$$[(x, y) \mid x \leftarrow [1, 2], y \leftarrow [3, 4]] = [(1, 3), (1, 4), (2, 3), (2, 4)].$$

In general, a comprehension has the form $[t \mid q]$, where t is a term and q is a qualifier. We use the letters t, u, v to range over terms, and p, q, r to range over qualifiers. A qualifier is either empty, Λ ; or a generator, $x \leftarrow u$, where x is a variable and u is a list-valued term; or a composition of qualifiers, (p, q) . Comprehensions are defined by the following rules:

- (1) $[t \mid \Lambda] = \text{unit } t,$
- (2) $[t \mid x \leftarrow u] = \text{map}(\lambda x \rightarrow t) u,$
- (3) $[t \mid (p, q)] = \text{join}[[t \mid q] \mid p].$

Peter Buneman *et al* (1991) – Comprehensions

A more verbose version of this query can also be written in SQL

```
SELECT  Name = p.Name, Mgr = d.Mgr
FROM    Emp p, Dept d
WHERE   p.D# = d.D#
```

We can put a different interpretation on the syntax of this query. In SQL, the symbols p and d are simply aliases for the relation names `Emp` and `Dept` respectively. interesting connections with what we shall develop. In our syntax this query is written:

```
{ [Name = p.Name, Mgr = d.Mgr] |
  \p <- Emp,
  \d <- Dept,
  p.DNum = d.DNum }
```

The syntactic form $\{e \mid c_1, c_2, \dots, c_n\}$ is a *comprehension*. It is an expression that denotes a collection – in

XQuery (2004) – FLWOR

W3C Working Draft

3.8 FLWOR Expressions

XQuery provides a feature called a FLWOR expression that supports iteration and binding of variables to intermediate results. This kind of expression is often useful for computing joins between two or more documents and for restructuring data. The name FLWOR, pronounced "flower", is suggested by the keywords `for`, `let`, `where`, `order by`, and `return`.

```
<authlist>
{
  for $a in fn:distinct-values($bib/book/author)
  order by $a
  return
    <author>
      <name> {$a} </name>
      <books>
        {
          for $b in $bib/book[author = $a]
          order by $b/title
          return $b/title
        }
      </books>
    </author>
}
</authlist>
```

XQuery (2004) — Formal Semantics

4.8.2 For expression

Static Type Analysis

A single `for` expression is typed as follows: First $Type_1$ of the iteration expression $Expr_1$ is inferred. Then the prime type of $Type_1$, $\text{prime}(Type_1)$, is computed. This is a union over all item types in $Type_1$ (See [\[8.4 Judgments for FLWOR and other expressions on sequences\]](#)). With the variable component of the static environment statEnv extended with $VarRef_1$ as type $\text{prime}(Type_1)$, the type $Type_2$ of $Expr_2$ is inferred. Because the `for` expression iterates over the result of $Expr_1$, the final type of the iteration is $Type_2$ multiplied with the possible number of items in $Type_1$ (one, ?, *, or +). This number is determined by the auxiliary type-function quantifier($Type_1$).

$$\frac{\text{statEnv} \vdash Expr_1 : Type_1}{\text{statEnv} + \text{varType}(VarRef_1 : \text{prime}(Type_1)) \vdash Expr_2 : Type_2}$$

$$\text{statEnv} \vdash \text{for } VarRef_1 \text{ in } Expr_1 \text{ return } Expr_2 : Type_2 \cdot \text{quantifier}(Type_1)$$

Part IV

Classical logic,
continuations,
and the Web

Andrei Kolmogorov (1925)

To an elementary formula Ξ there corresponds in pseudomathematics the formula Ξ^* , which expresses the double negation of Ξ :

$$(48) \quad \Xi^* \equiv \overline{\Xi}.$$

In what follows we shall, for convenience, denote the double negation of Ξ by $n\Xi$.

To the formula of the n th order $F(\Xi_1, \Xi_2, \dots, \Xi_k)$, where $\Xi_1, \Xi_2, \dots, \Xi_k$ are formulas of the $(n-1)$ th order at most, there corresponds in pseudomathematics the formula $F(\Xi_1, \Xi_2, \dots, \Xi_k)^*$ such that

$$(49) \quad F(\Xi_1, \Xi_2, \dots, \Xi_k)^* \equiv nF(\Xi_1^*, \Xi_2^*, \dots, \Xi_k^*),$$

$\Xi_1^*, \Xi_2^*, \dots, \Xi_k^*$ being regarded as already determined. For example, to the formula

$$a = b \rightarrow \{A(a) \rightarrow B(a)\}$$

there corresponds in pseudomathematics the formula

$$n[n(a = b) \rightarrow n\{nA(a) \rightarrow nB(a)\}].$$

Gordon Plotkin (1975)

We begin with a simulation of call-by-value by call-by-name. Given a call-by-value language with its Constapply_v , Eval_v and λ_v , we consider the call-by-name language whose variables are those of the given language together with three others, κ , α and β say, and whose list of variables for the substitution prefix is that of the given language. Its Constapply will be given in a little while. First the term simulation map $M \mapsto \bar{M}$ sending terms in the call-by-value language to the call-by-name language is given by the recursive definition:

$$\bar{a} = \lambda\kappa.(xa)$$

$$\bar{x} = \lambda\kappa.\kappa x$$

$$\overline{\lambda x M} = \lambda\kappa.(\kappa(\lambda x \bar{M}))$$

$$\overline{MN} = \lambda\kappa.(\bar{M}(\lambda\alpha\bar{N}(\lambda\beta\alpha\beta\kappa))).$$

Constapply_N is given by:

$$\text{Constapply}_N(a, b) = \overline{\text{Constapply}_v(a, b)}$$

Philip Wadler (2000)

$(\beta\&)$	$\langle V, W \rangle \bullet \text{fst}[K]$	\longrightarrow_v	$V \bullet K$
$(\beta\&)$	$\langle V, W \rangle \bullet \text{snd}[L]$	\longrightarrow_v	$W \bullet L$
$(\beta\vee)$	$\langle V \rangle \text{inl} \bullet [K, L]$	\longrightarrow_v	$V \bullet K$
$(\beta\vee)$	$\langle W \rangle \text{inr} \bullet [K, L]$	\longrightarrow_v	$W \bullet L$
$(\beta\neg)$	$[K] \text{not} \bullet \text{not}\langle M \rangle$	\longrightarrow_v	$M \bullet K$
$(\beta\supset)$	$\lambda x. N \bullet V @ L$	\longrightarrow_v	$V \bullet x.(N \bullet L)$
(βL)	$V \bullet x.(S)$	\longrightarrow_v	$S\{V/x\}$
(βR)	$(S).\alpha \bullet K$	\longrightarrow_v	$S\{K/\alpha\}$
$(\beta\&)$	$\langle M, N \rangle \bullet \text{fst}[P]$	\longrightarrow_n	$M \bullet P$
$(\beta\&)$	$\langle M, N \rangle \bullet \text{snd}[Q]$	\longrightarrow_n	$N \bullet Q$
$(\beta\vee)$	$\langle M \rangle \text{inl} \bullet [P, Q]$	\longrightarrow_n	$M \bullet P$
$(\beta\vee)$	$\langle N \rangle \text{inr} \bullet [P, Q]$	\longrightarrow_n	$N \bullet Q$
$(\beta\neg)$	$[K] \text{not} \bullet \text{not}\langle M \rangle$	\longrightarrow_n	$M \bullet K$
$(\beta\supset)$	$\lambda x. N \bullet M @ Q$	\longrightarrow_n	$M \bullet x.(N \bullet Q)$
(βL)	$M \bullet x.(S)$	\longrightarrow_n	$S\{M/x\}$
(βR)	$(S).\alpha \bullet P$	\longrightarrow_n	$S\{P/\alpha\}$

Philip Wadler (2000)

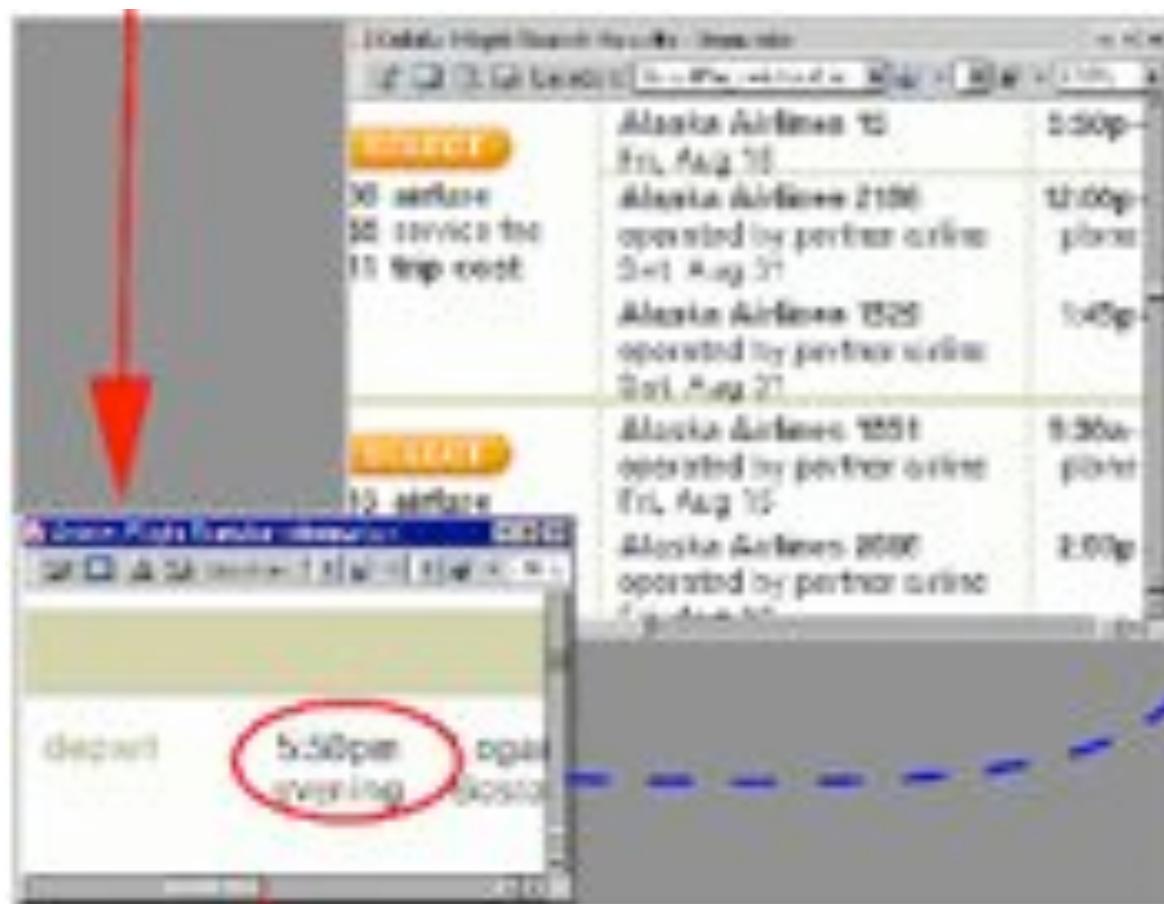
$$\begin{array}{c}
 \frac{}{x : A \rightarrow I\!x : A} \text{IdR} \quad \frac{\alpha : A \rightarrow \alpha : A}{\alpha : A \rightarrow \alpha : A} \text{IdL} \\
 \frac{\Gamma \rightarrow \Theta \mid M : A \quad \Gamma \rightarrow \Theta \mid N : B}{\Gamma \rightarrow \Theta \mid \langle M, N \rangle : A \& B} \& R \quad \frac{K : A \rightarrow \Gamma \rightarrow \Theta}{\text{fst}[K] : A \& B \rightarrow \Gamma \rightarrow \Theta} \text{fst} \\
 \frac{L : B \rightarrow \Gamma \rightarrow \Theta}{\text{snd}[L] : A \& B \rightarrow \Gamma \rightarrow \Theta} \& L \\
 \frac{\Gamma \rightarrow \Theta \mid M : A}{\Gamma \rightarrow \Theta \mid (M)\text{inl} : A \vee B} \text{inl} \quad \frac{\Gamma \rightarrow \Theta \mid N : B}{\Gamma \rightarrow \Theta \mid (N)\text{inr} : A \vee B} \vee R \quad \frac{K : A \rightarrow \Gamma \rightarrow \Theta \quad L : B \rightarrow \Gamma \rightarrow \Theta}{[K, L] : A \vee B \rightarrow \Gamma \rightarrow \Theta} \vee L \\
 \frac{K : A \rightarrow \Gamma \rightarrow \Theta}{\Gamma \rightarrow \Theta \mid [K]\text{not} : \neg A} \neg R \quad \frac{\Gamma \rightarrow \Theta \mid M : A}{\text{not}(M) : \neg A \rightarrow \Gamma \rightarrow \Theta} \neg L \\
 \frac{x : A, \Gamma \rightarrow \Theta \mid N : B}{\Gamma \rightarrow \Theta \mid \lambda x. N : A \supset B} \supset R \quad \frac{\Gamma \rightarrow \Theta \mid M : A \quad L : B \rightarrow \Delta \rightarrow \Lambda}{M @ L : A \supset B \rightarrow \Gamma, \Delta \rightarrow \Theta, \Lambda} \supset L \\
 \frac{\Gamma \vdash S \vdash \Theta, \alpha : A}{\Gamma \rightarrow \Theta \mid (S), \alpha : A} \text{RI} \quad \frac{x : A, \Gamma \vdash S \vdash \Theta}{x, (S) : A \rightarrow \Gamma \rightarrow \Theta} \text{LI} \\
 \frac{\Gamma \rightarrow \Theta \mid M : A \quad K : A \rightarrow \Delta \rightarrow \Lambda}{\Gamma, \Delta \vdash M \bullet K \vdash \Theta, \Lambda} \text{Cut}
 \end{array}$$

Orbitz: Two flights

Orbitz flight search results - Domestic		
<input type="checkbox"/> SELECT	Alaska Airlines 15 Fri, Aug 16	5:50p -
<input type="checkbox"/> SELECT	Alaska Airlines 2108 operated by partner airline Sat, Aug 31	7:00p - plane 6
<input type="checkbox"/> SELECT	Alaska Airlines 1529 operated by partner airline Sat, Aug 31	1:45p -
<input type="checkbox"/> SELECT	Alaska Airlines 1551 operated by partner airline Fri, Aug 16	9:30a - 1 plane 7
<input type="checkbox"/> SELECT	Alaska Airlines 2086 operated by partner airline Sat, Aug 31	2:00p -

Graunke, Findler, Krishnamurthi, Felleisen (ESOP 2003)

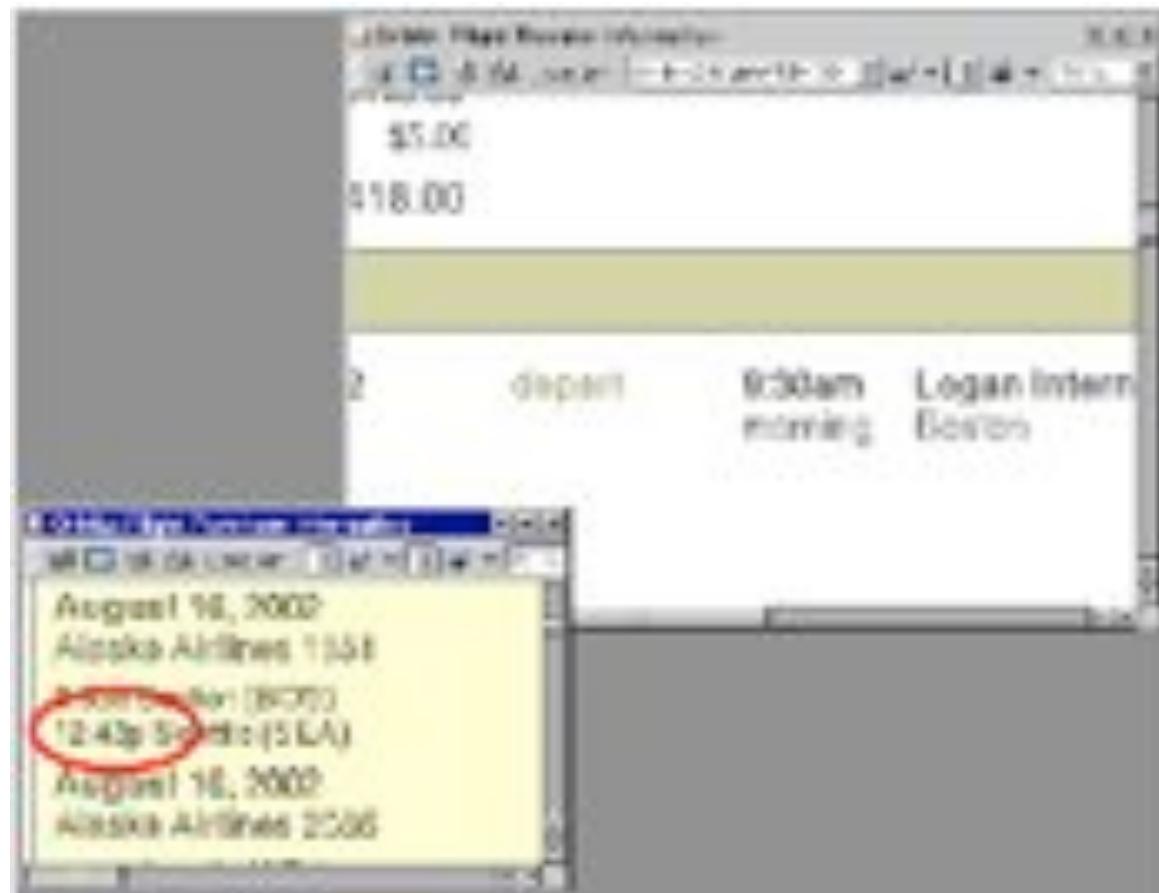
Orbitz: Clone and submit first



Orbitz: Submit second



Orbitz: Select first – problem!



Burstall, MacQueen, and Sannella (1980) — Hope

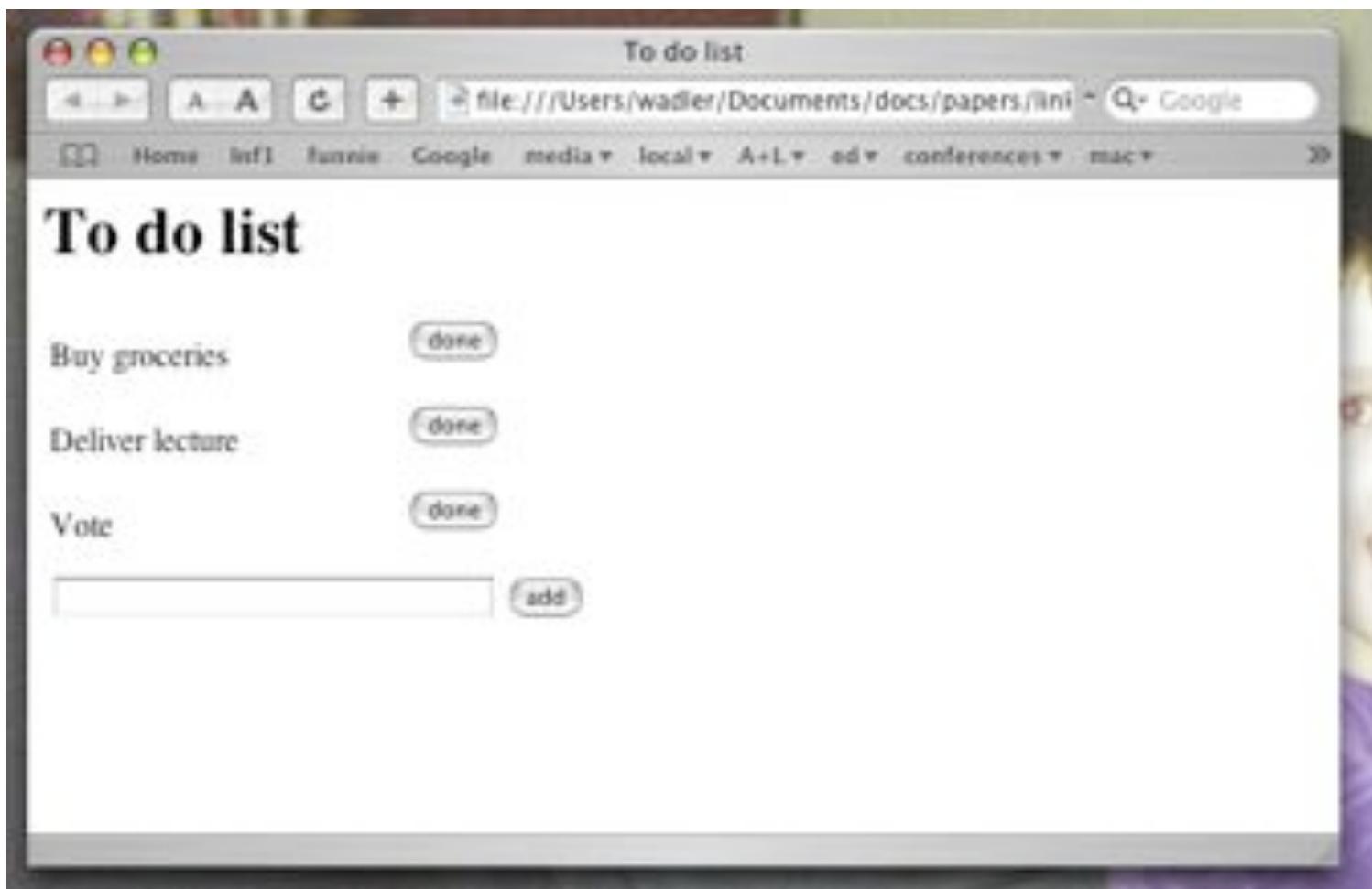


Burstall, MacQueen, and Sannella (1980) — Hope



Wadler and Yallop (2005) — Links

```
main() { todo([]) }
todo(items) {
    <html><body>
        <h1>Items to do</h1>
        <table>{
            for item in items return
                <tr>
                    <td>{item}</td>
                    <td>
                        <form l:action="{todo(items\\[item])}">
                            <input type="submit" value="done"/>
                        </form>
                    </td>
                </tr>
        }</table>
        <form l:action="{todo(items++[new])}">
            <input l:name="{new}" type="text" size="40">
            <input type="submit" value="add"/>
        </form>
    </body></html>
}
```



Part V

Conclusions



Kinds of coincidence

Historical confluence of great minds — Hume, Hutton, Smith



Geographical shape of continents



Astronomical size of sun and moon from earth



More than a coincidence?

second-order logic

polymorphism

Java

modal logic

monads

XML

classical logic

continuations

Links

More than a coincidence?

second-order logic

polymorphism

Java

modal logic

Milner

XML

classical logic

Moggi,Buneman

continuations

Links

Plotkin

Scottish Programming Language Seminar



Dec 2004 University of Glasgow
Mar 2005 University of Edinburgh
Jun 2005 Heriot-Watt University
Sep 2005 *University of St Andrews?*

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Adam and Leora for their books



Catherine for the tie

You for listening